

Manuscript submitted to Journal of Robotics



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Journal of Robotics <radwa.amin@hindawi.com> [in](#)
To: Daniel Sutopo Pamungkas

Tue 1/12/2021 10:52 PM

Dear Dr. Pamungkas,

[Congratulations](#), the manuscript titled "The Human Walking Gait Cycle for Assistive Torque Generation on Hip Joint of Lower Limb Exoskeleton" has been successfully submitted to Journal of Robotics.

We will confirm this submission with all authors of the manuscript, but you will be the primary recipient of communications from the journal. As submitting author, you will be responsible for responding to editorial queries and making updates to the manuscript.

In order to view the status of the manuscript, please visit the manuscript details page.

Thank you for submitting your work to Journal of Robotics.

[MANUSCRIPT DETAILS](#)

Kind regards,
Radwa Amin
Journal of Robotics

This email was sent to daniel@polibatam.ac.id. You have received this email in regards to the account creation, submission, or peer review process of a submitted paper, published by Hindawi Limited.
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Authors' Feedback Needed : 5561600



Daniel Sutopo Pamungkas
To: Lester Calpito <lester.calpito@hindawi.com>

Tue 1/19/2021 9:11 AM

Dear Lester Calpito,

Thank you for your feedback. I have been mended all inaccuracy.

For my name, I have updated the profile but the system does not change so that I have modified the articles without using my middle name. Can you accept these changes?

If there are any corrections that we have to do, please inform me.

Warm Regards,

Daniel S Pamungkas

[...](#)



Lester Calpito <lester.calpito@hindawi.com>
To: Daniel Sutopo Pamungkas

Tue 1/19/2021 5:55 AM

Dear Dr. Daniel Pamungkas,

Thank you for your email.

The name format on the System and PDF file is different.

System: Hendawan Soebakti, Daniel Pamungkas

PDF: Hendawan Soebhakti, Daniel Sutopo Pamungkas

Please confirm the correct and final author's name format and affiliations and update the records in the system.

We are encountering problems with the email address "riska@polibatam.ac.id" that has been provided for Dr. Riska Analia as it continuously states that the address couldn't be found or is unable to receive mail. Please provide another verified email address or institutional email address for Dr. Riska Analia. Also kindly check for possible typographical errors in the email address provided.

Best Regards,
Lester

5561600: Revision requested



Li Changsheng <support@hindawi.com>
To: Daniel Sutopo Pamungkas

👍 ↩️ ⏪ ⏩ ⋮
Fri 5/14/2021 8:57 AM

Dear Pamungkas Daniel,

In order for your submission "Use of the Human Walking Gait Cycle for Assistive Torque Generation for the Hip Joint of a Lower Limb Exoskeleton" to Journal of Robotics to proceed to the review process, there needs to be a revision.

Reasons & Details:

“

Major revision is recommended to address the reviewer's comments.

For more information about what is required, please click the link below.

MANUSCRIPT DETAILS

Kind regards,
Li Changsheng

Journal of Robotics

Re: Hindawi Author Reminder – submit your revised files



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Jane Rose Mercado <kaviya.sathiyababu@hindawi.com>

To: Daniel Sutopo Pamungkas

👍 ↩️ ⏪ ⏩ ⋮

Wed 10/6/2021 11:29 AM

Dear Dr. Pamungkas,

Thank you for your request to extend the revision deadline for your manuscript.

I have forwarded your request on to the EA of the journal, who will be able to assist you further with your enquiry.

Best regards,

Jane Rose

Jane Rose Mercado
Support Specialist

Re: 5561600: Regarding Submission of Revised Manuscript



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Kaviya Sathiyar Babu <kaviya.sathiyababu@hindawi.com>

To: Daniel Sutopo Pamungkas



Sun 11/7/2021 8:21 PM

Dear Dr. Pamungkas,

Many thanks for submitting your revised manuscript.

Please be assured that we shall expedite the review process of your manuscript.

Please let me know for further assistance.

Best regards,
Kaviya

Kaviya Sathiyar Babu
Editorial Assistant



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5561600: Revision requested



Li Changsheng <support@hindawi.com>

To: Daniel Sutopo Pamungkas

80%



Reset

Tue 8/31/2021 11:30 AM

Dear Pamungkas Daniel,

In order for your submission "Use of the Human Walking Gait Cycle for Assistive Torque Generation for the Hip Joint Exoskeleton" to Journal of Robotics to proceed to the review process, there needs to be a revision.

Reasons & Details:

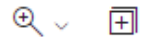


Minor revision is required according to the comments of the reviewer.

For more information about what is required, please click the link below.

MANUSCRIPT DETAILS

Re: 5561600: Regarding Submission of Revised Manuscript



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Kaviya Sathiyababu <kaviya.sathiyababu@hindawi.com>

To: Daniel Sutopo Pamungkas



Sun 11/7/2021 8:21 PM

Dear Dr. Pamungkas,

Many thanks for submitting your revised manuscript.

Please be assured that we shall expedite the review process of your manuscript.

Please let me know for further assistance.

Best regards,
Kaviya

Your manuscript has been accepted for publication



Journal of Robotics <kaviya.sathiyababu@hindawi.com>

To: Daniel Sutopo Pamungkas



Fri 11/12/2021 5:32 PM

Dear Dr. Pamungkas,

I am delighted to inform you that the review of your Research Article 5561600 titled Use of the Human Walking Gait Cycle for Assistive Torque Generation for the Hip Joint Exoskeleton has been completed and your article has been accepted for publication in Journal of Robotics.

Please visit the manuscript details page to review the editorial notes and any comments from external reviewers. If you have deposited your manuscript on a preprint server, now would be a good time to update it with the accepted version. If you have not deposited your manuscript on a preprint server, you are free to do so.

We will now check that all of your files are complete before passing them over to our production team for processing. We will let you know soon should we require any further information.

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Files requested - Use of the Human Walking Gait Cycle for Assistive Torque Generation for the Hip Joint Exoskeleton



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Quality Checking Team <support@hindawi.com>
To: Daniel Sutopo Pamungkas



Fri 11/26/2021 2:08 PM

Dear Dr. Daniel Pamungkas,

Regarding your manuscript Use of the Human Walking Gait Cycle for Assistive Torque Generation for the Hip Joint Exoskeleton 5561600, we would be grateful if you could please address the following:

Additional Comments:

1. The author name Dr. Abdullah Sani is listed as a different name on the submission system. Please provide us with the final name format and final version of the manuscript word file updated with the correct name formats of all the authors for us to proceed further. 2. Figures 1, 3, and 4 differ between the manuscript word file and the figure file. Please provide us with the final version of figures 1, 3, 4, and the final version of the manuscript (word file) updated with the final version of the figures for us to proceed further. 3. Figures 5, 8, 9, 10, 11, and 12 cannot be edited. We need to be able to modify font type and size, lines, strokes, and scales to apply our in-house style. The figures should be in the original or default formats in which they were created before being converted or inserted into any other formats. Please provide the better quality version of figures in a separate PDF, Visio, Word, Excel, or PowerPoint file which can be edited. Please note that jpg, bmp, png, and tif files cannot be edited by default. 4. The resolution of figures 5, and 8 are insufficient and the text inside the figure is of low visual quality. Please provide us with a better quality version of figures which includes clear labels and can be edited."

1. Click on the manuscript title Use of the Human Walking Gait Cycle for Assistive Torque Generation for the Hip Joint Exoskeleton, which will show the status "Submit Updates"
2. Click on the "Submit Quality Check Updates" button to show the manuscript details and files
3. The manuscript information will be pre-filled as you submitted the manuscript, so you will not need to complete the entire submission again. Scroll down the page until you reach the area(s) that need updating
4. If the manuscript file needs updating then go to the 'Manuscript Files' section and

Files requested - Use of the Human Walking Gait Cycle for Assistive Torque Generation for the Hip Joint Exoskeleton



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Quality Checking Team <support@hindawi.com>
To: Daniel Sutopo Pamungkas



Sat 11/27/2021 5:04 PM

Dear Dr. Daniel Pamungkas,

Regarding your manuscript Use of the Human Walking Gait Cycle for Assistive Torque Generation for the Hip Joint Exoskeleton 5561600, we would be grateful if you could please address the following:

Additional Comments:

This email is just for your information - no action is needed. We are uploading the figure files on your behalf, so please don't take any further action.

1. Click on the manuscript title Use of the Human Walking Gait Cycle for Assistive Torque Generation for the Hip Joint Exoskeleton, which will show the status "Submit Updates"
2. Click on the "Submit Quality Check Updates" button to show the manuscript details and files
3. The manuscript information will be pre-filled as you submitted the manuscript, so you will not need to complete the entire submission again. Scroll down the page until you reach the area(s) that need updating
4. If the manuscript file needs updating then go to the 'Manuscript Files' section, and click the small bin icon next to the manuscript file. This will delete the file. You can then upload the new updated file
5. When all necessary changes have been made, click the green "Submit manuscript" button at the bottom of the screen, and this will return the manuscript to the Hindawi team.

Kind regards,
Quality Checking Team

5561600: Galley Proofs



Journal of Robotics <production.b@hindawi.com>

To: Daniel Sutopo Pamungkas

Cc: Susanto; jshferdinand@gmail.com; janhong.jh@gmail.com; Riska Analia; Hendawan Soebhakti; Abdullah Sani +2 others



Sat 12/4/202

Dear Dr. Daniel,

I am pleased to let you know that the first set of galley proofs of your Research Article 5561600 titled "Use of the Human Walking Gait Cycle for Assistive Torque Gene for the Hip Joint Exoskeleton," is ready. You can apply your corrections directly to the manuscript with the Online Proofing System (OPS).

Using the OPS, you can quickly and easily make corrections directly to your galley proofs and submit these corrections with a single click.

<https://ops.hindawi.com/author/5561600/>

Please note, although all authors can view the proof, it is only the submitting author (the author addressed in this email) who has the ability to edit and submit the corrections. However, the submitting author can log in to the OPS and re-assign the proof to another author if necessary. The submitting author will need to log in with email address included on this email.

If a new corresponding author is added, they must log into their manuscript tracking system account and add their ORCID ID. Any additional ORCID IDs added on during proofing will also need to be updated on that author's account. Delays can occur if this isn't done.

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5561600: Your article has been published



① You forwarded this message on Wed 12/8/2021 8:20 PM



Kaviya Sathiyar Babu <kaviya.sathiyarbabu@hindawi.com>

To: Daniel Sutopo Pamungkas



Wed 12/8/2021 8:17 PM

Dear Dr. Pamungkas,

I am pleased to let you know that your article has been published in its final form in "Journal of Robotics."

Daniel Pamungkas, "Use of the Human Walking Gait Cycle for Assistive Torque Generation for the Hip Joint Exoskeleton," Journal of Robotics, vol. 2021, Article ID 5561600, 12 pages, 2021. <https://doi.org/10.1155/2021/5561600>.

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Thank you for publishing your article with Hindawi, and we hope that you continue to choose Journal of Robotics as a home for your research.

Best regards,